

Highly Accelerated Life Testing

David S. Parsons
Jet Propulsion Laboratory
California Institute of Technology
Pasadena, CA 91109, USA

The research described in this publication was carried out at the Jet Propulsion Laboratory, California Institute of Technology, under a contract with the National Aeronautics and Space Administration. Government sponsorship acknowledged.



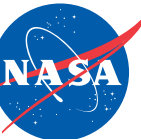
Overview

- HALT/HASS Overview
 - Highly Accelerated Life Testing
 - Highly Accelerated Stress Screening
- Challenges with HALT
- Simulating a coring environment on Mars
- HALT as part of an environment test program



Caveats

- I have not performed a true HALT/HASS program.
 - Utilized HALT chamber to simulate a coring environment on Mars.
- In preparation for this test, attended a HALT training seminar at Hobbs Engineering in Denver, Colorado.
- Unless otherwise stated, most of the presentation materials are my interpretation & understanding of HALT.



HALT/HASS Overview



HALT/HASS

HALT: Highly Accelerated Life Testing

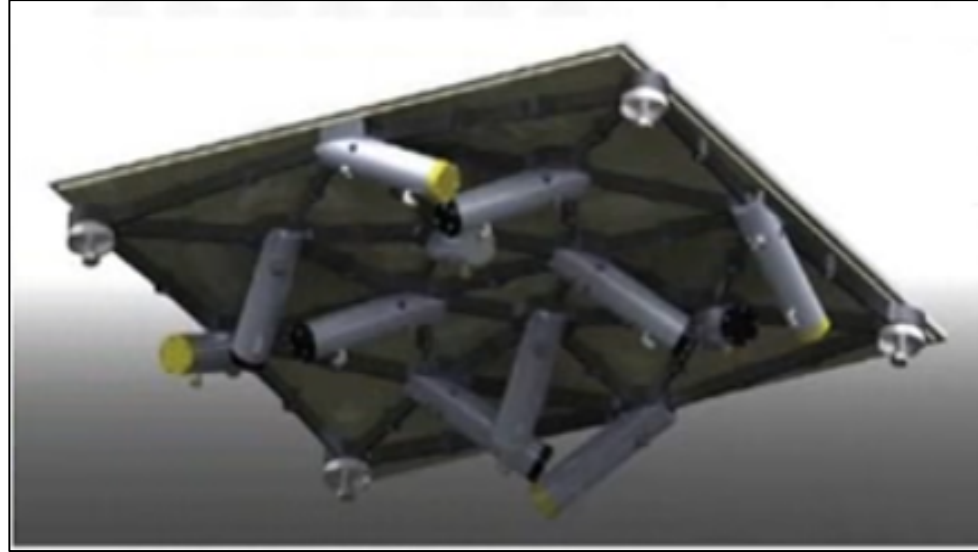
- HALT is the concept of iteratively developing a component through identifying failure modes as quickly as possible, implementing a design change/corrective action, and repeating the process until a robust design is developed.
- HALT is implemented by exposing the prototype to increasing magnitudes of
 - Temperature
 - Vibration/Repetitive-Shock
 - Voltage (not covered in this presentation)Until the prototype fails.
- Failure includes both Operational Limit (intermittent functional failure) and Destruction Limit (permanent failure).
- ***HALT is not an environmental test!***

HASS: Highly Accelerated Stress Screening

- After component maturity, HASS is used to screen components for latent failures after assembly.
 - Analogous to minimum workmanship.
- HASS is performed within the Operation Limits identified during HALT.



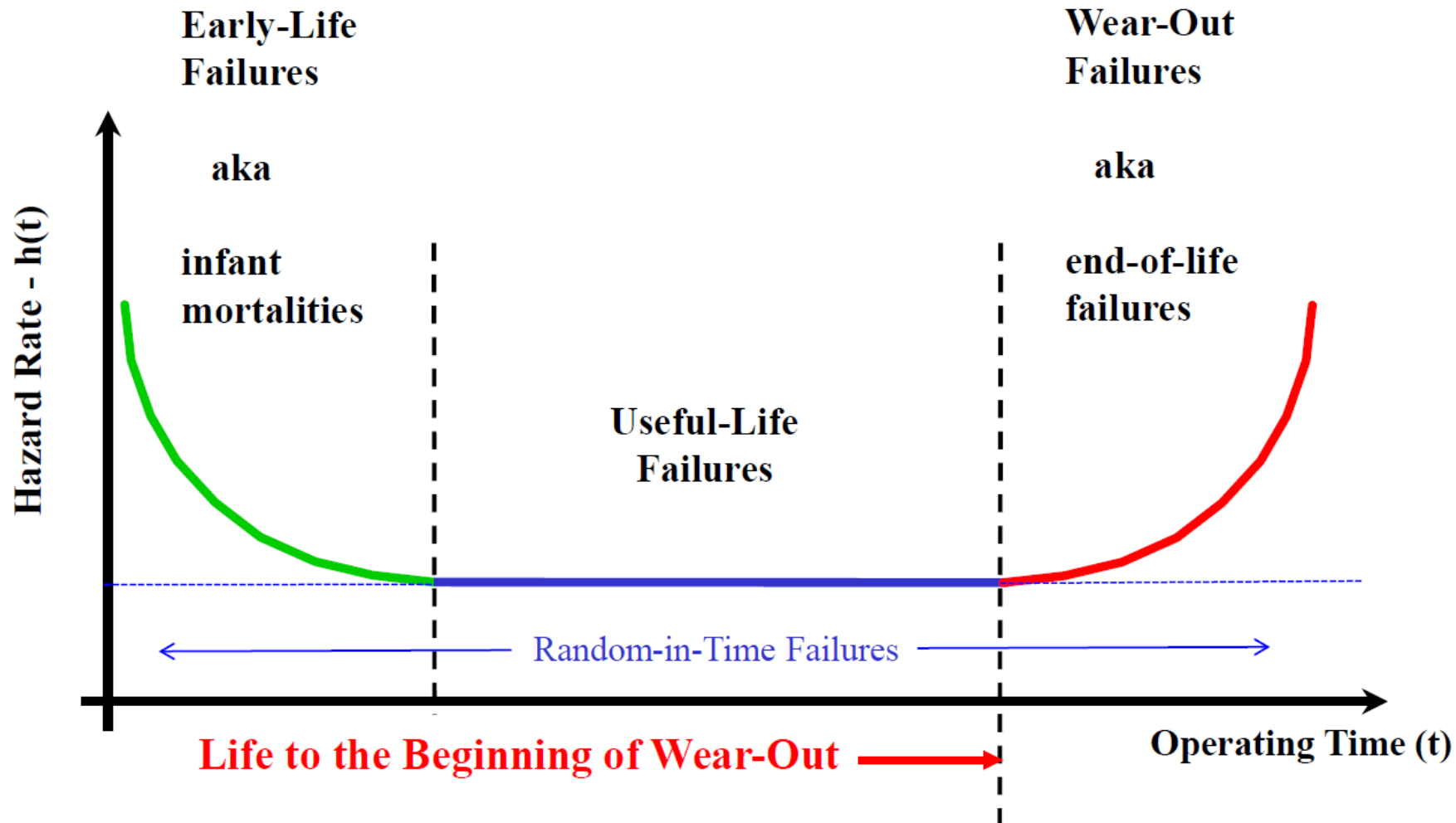
HALT Chamber



Underside of repetitive shock table with pneumatic actuator arrangement.

- Key differences from shaker table:
 - Semi-rigid table vs “infinite” impedance.
 - Single control accel for overall Grms control.
- Does offer live monitoring capability for hardware condition monitoring.

HALT: Robustness



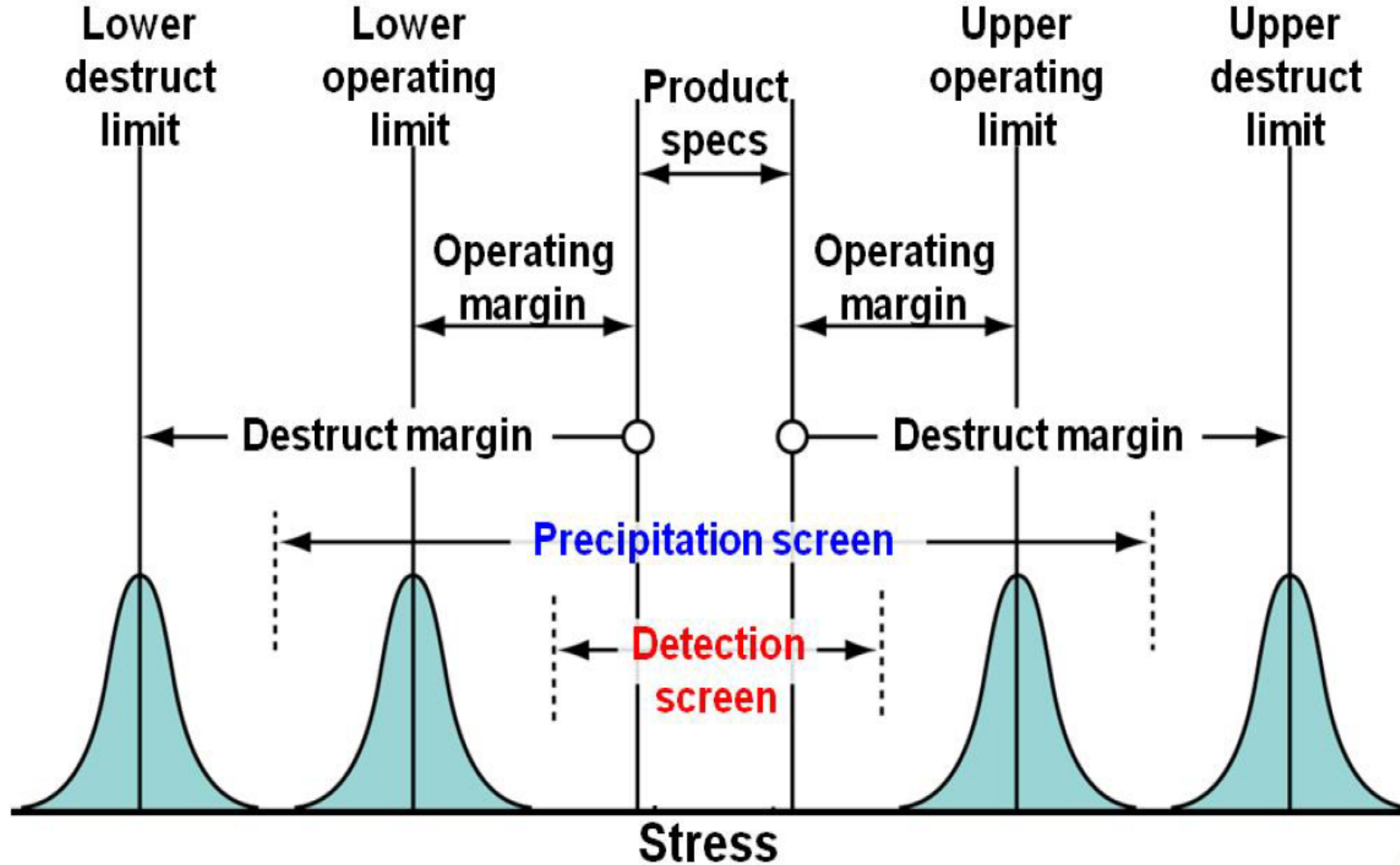
Provided courtesy of Aldo Fucinari, Rapid Discovery Systems

SCLV Dynamics Environment Workshop, 4 June, 2019

© 2019 California Institute of Technology. Government sponsorship acknowledged.



HALT/HASS Limits



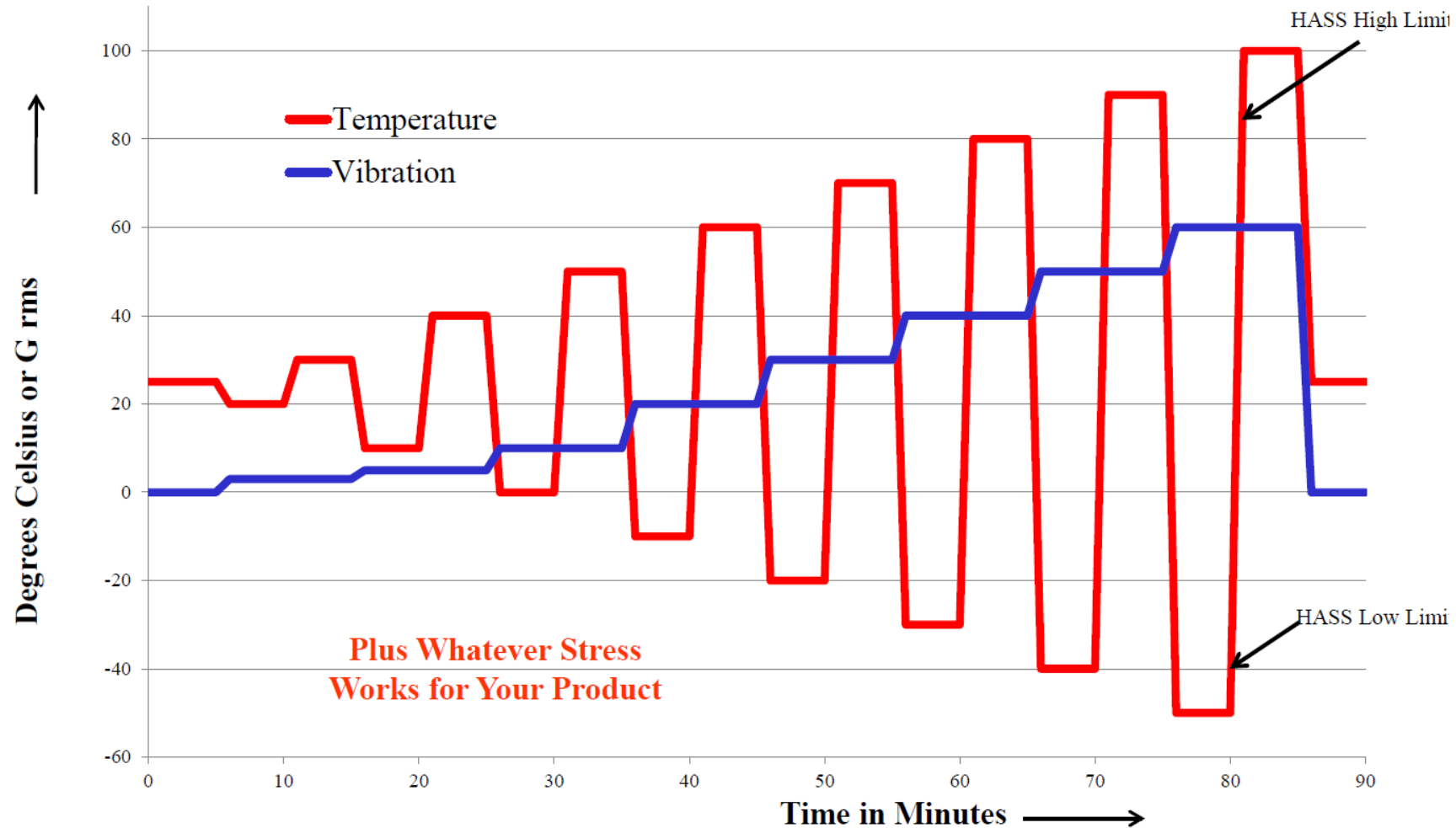
Provided courtesy of Aldo Fucinari, Rapid Discovery Systems

SCLV Dynamics Environment Workshop, 4 June, 2019

© 2019 California Institute of Technology. Government sponsorship acknowledged.



Example of HALT Vibration/Temperature Profile



Provided courtesy of Aldo Fucinari, Rapid Discovery Systems

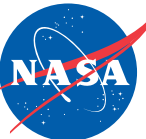
SCLV Dynamics Environment Workshop, 4 June, 2019

© 2019 California Institute of Technology. Government sponsorship acknowledged.



Challenges with HALT

- Thought must be put into the fixture design to ensure that prototype is properly excited across the frequency spectrum.
 - The fixture itself can influence the environment seen on the prototype.
- Must iteratively fail prototypes. This could be cost prohibitive for single-build components/assemblies.
- Limited control of repetitive shock environment.
- Fault/Failure detection is critical to making improvements to prototypes.
 - Must be able to identify:
 - Hard failures
 - Soft failures
 - Intermittent failures

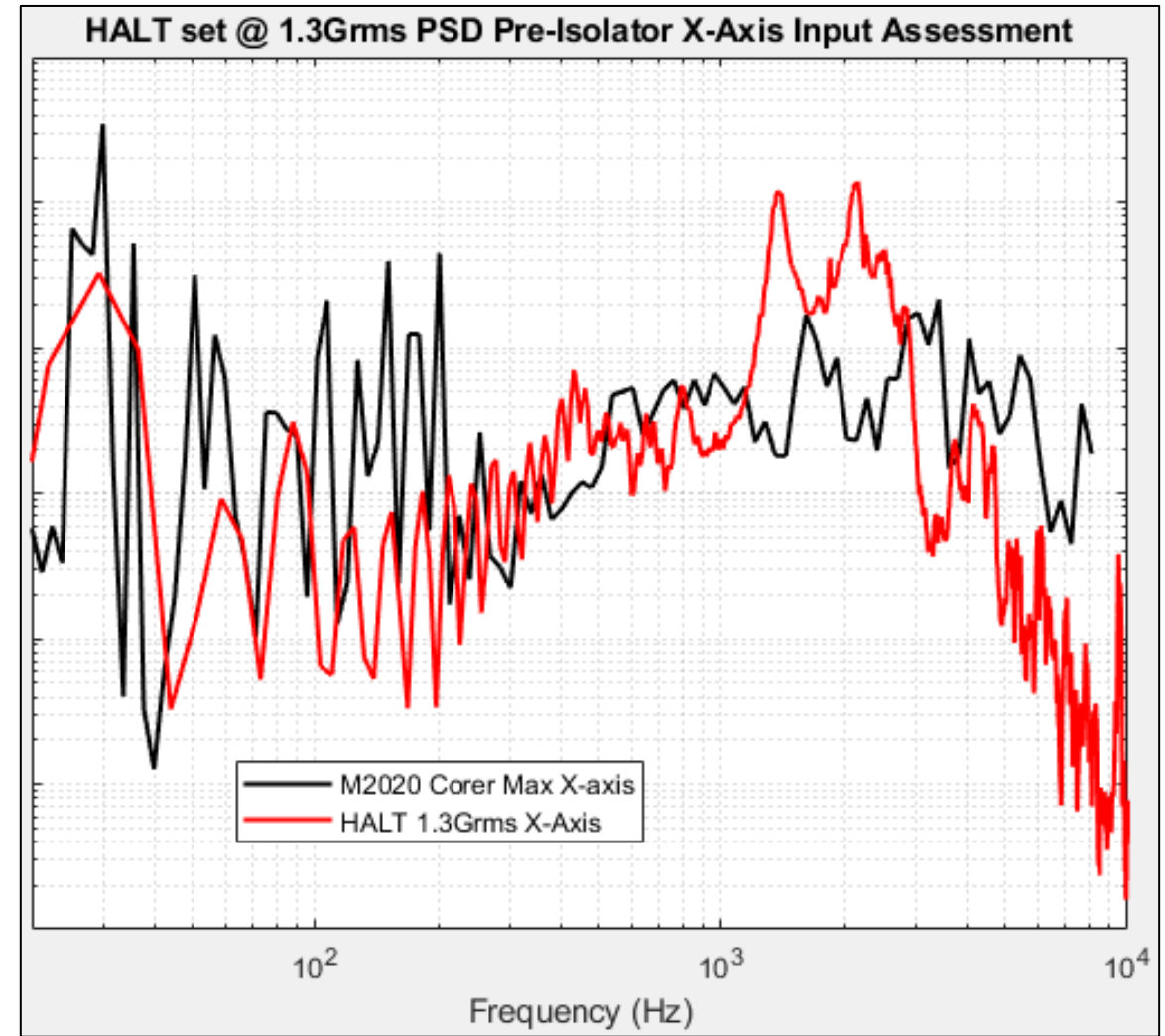
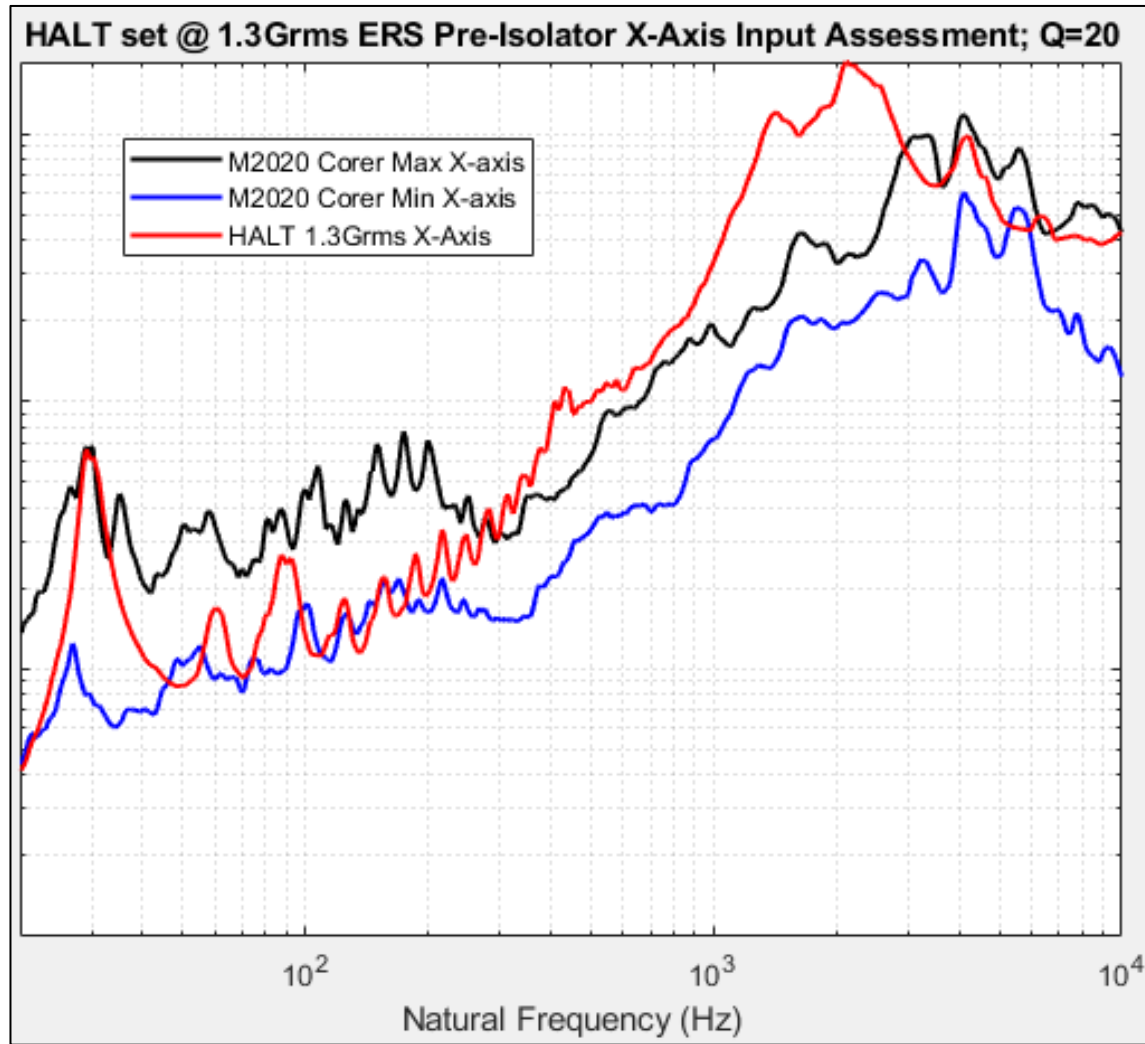


Simulating a Coring Environment

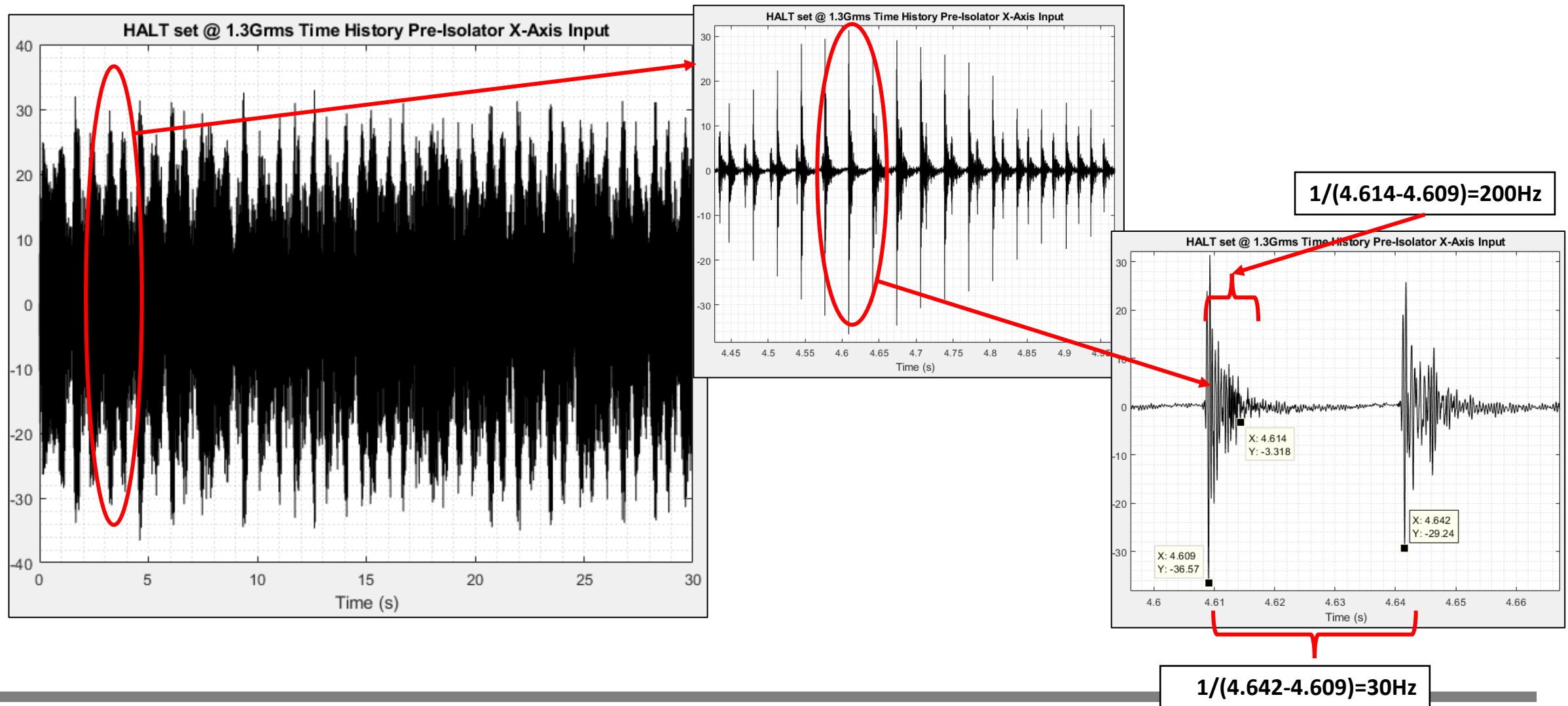
An atypical use of HALT Chamber Capabilities



Simulating a Coring Environment



Simulating a Coring Environment Cont'd...

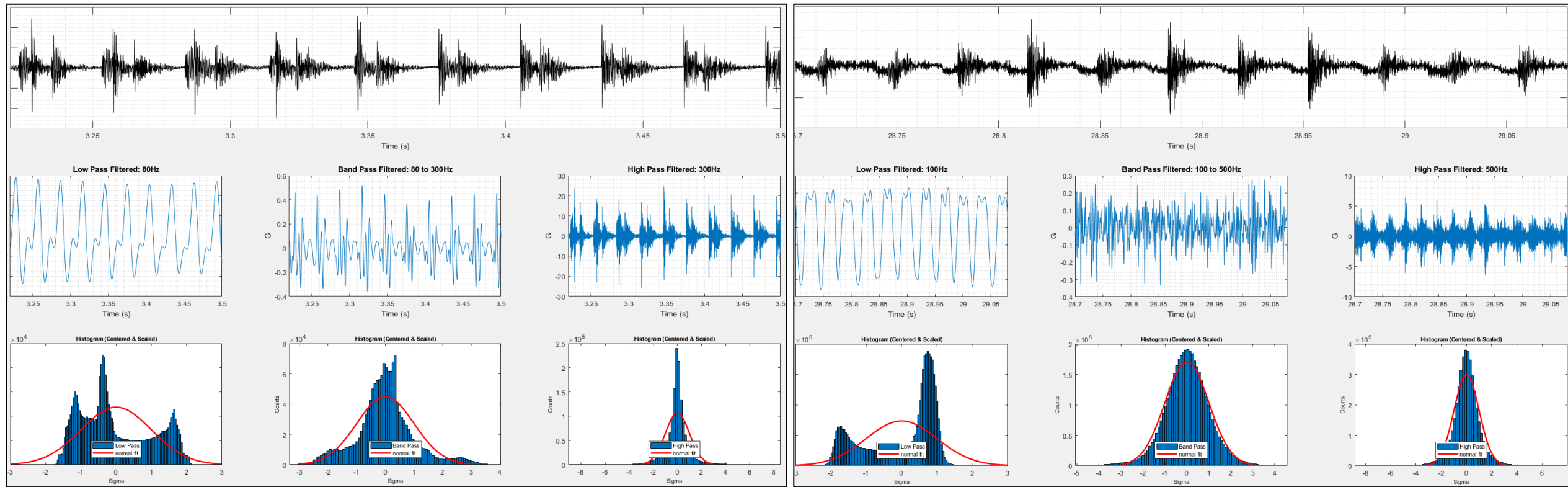


SCLV Dynamics Environment Workshop, 4 June, 2019

© 2019 California Institute of Technology. Government sponsorship acknowledged.



Coring Simulation Cont'd... Temporal Assessment



HALT

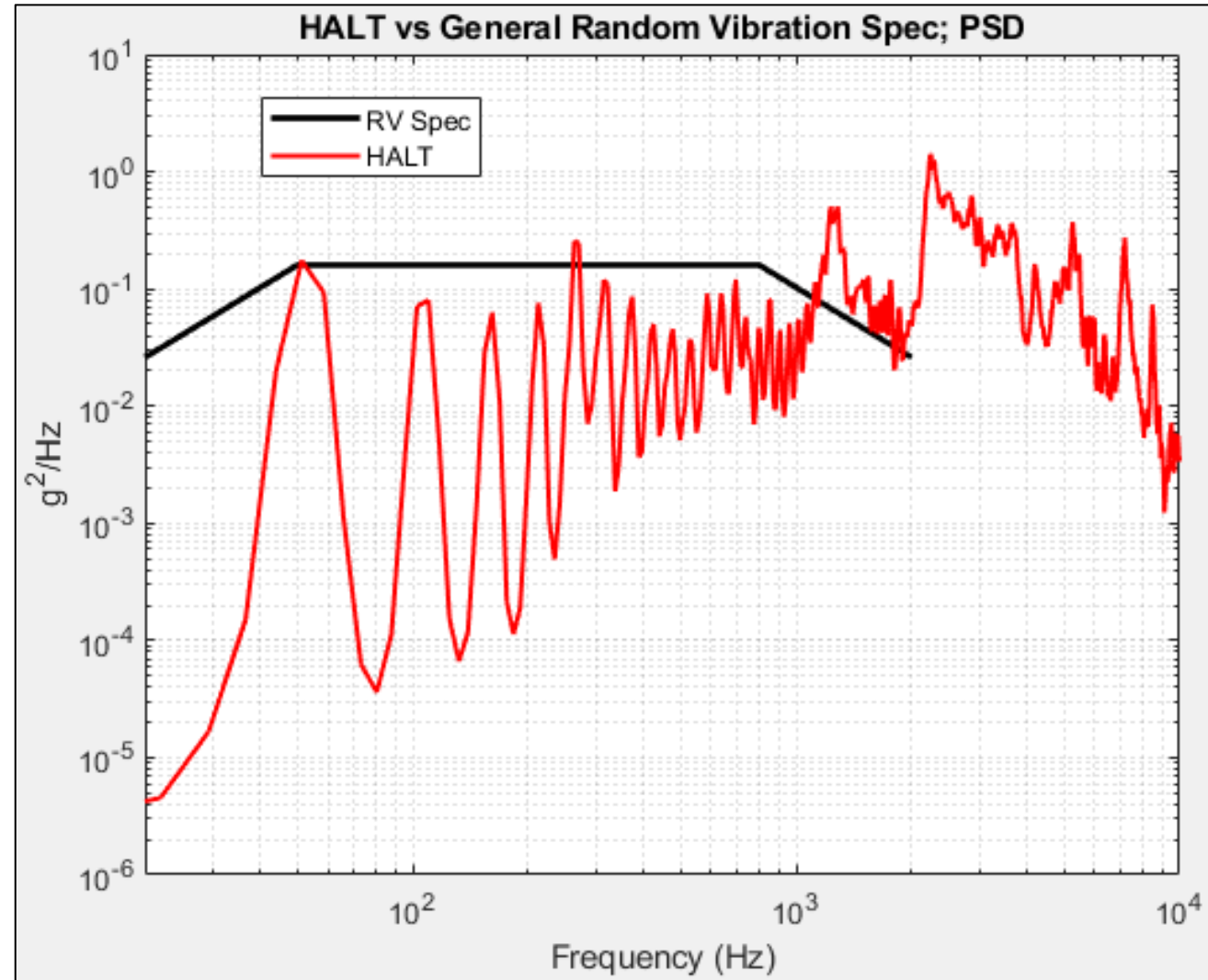
Corer

HALT & Environment Testing



Typical HALT PSD Compared to General Spec

- HALT does not need to be repeated ad infinitum:
 - Once component can withstand HALT levels at or above MPE, could stop process; however, this limits value of HASS.
- Majority of power is above 1kHz & is multi-axis excitation.
- HALT & HASS lends itself better to components that can be prototyped and multiple will be used. E.g. cable connectors, actuator motors, etc.



Summary

- HALT/HASS testing is a testing/development philosophy which emphasizes hardware robustness over designing hardware to a specific environment requirement.
 - *HALT is not a replacement to an environmental test program.*
- While this method may have limited value for single-development hardware, there are likely niche application within spacecraft/launch vehicle development in which HALT/HASS would be beneficial and perhaps more efficient than traditional development methods.
- While JPL has primarily used HALT to simulate a Mars coring environment, moving forward JPL is considering applications in which HALT/HASS would offer advantages over the traditional approach.



QUESTIONS?



BACKUP



HOBBS ENGINEERING

A DIVISION OF QUALMARK

HALT & HASS SEMINAR PLUS WORKSHOP

Aldo Fucinari – Instructor

Aldo Fucinari – © 2017 Hobbs Engineering a division of Qualmark Corporation

0

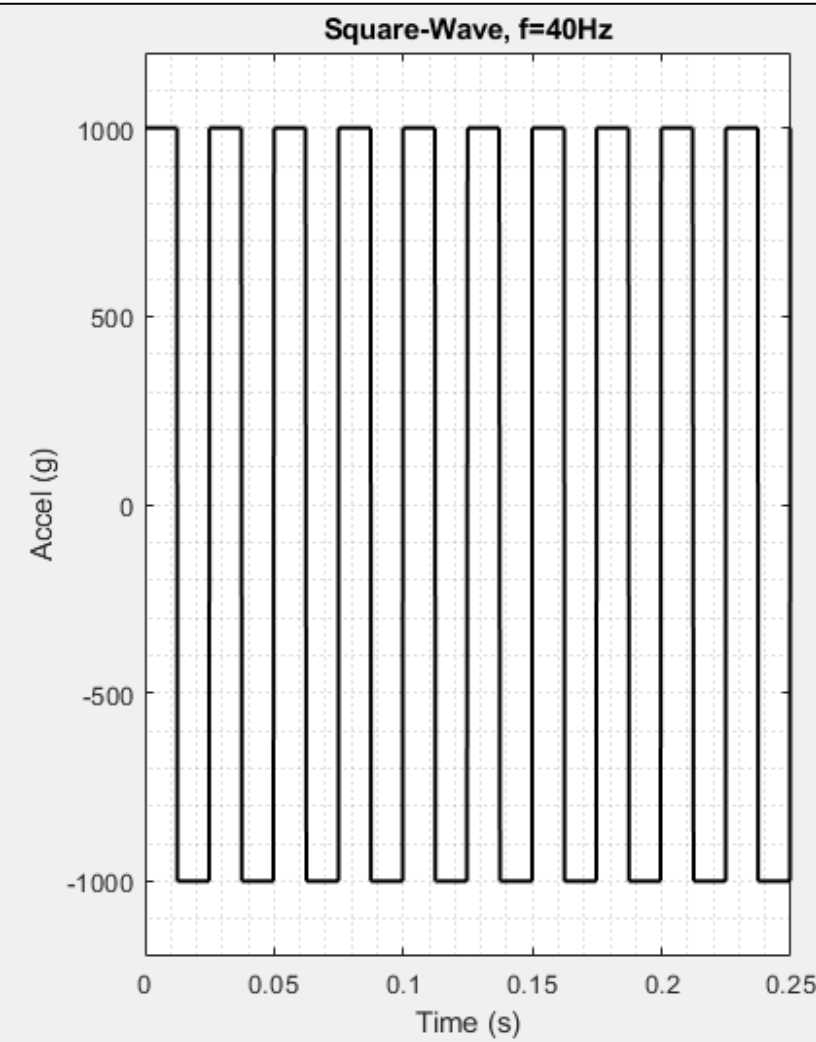
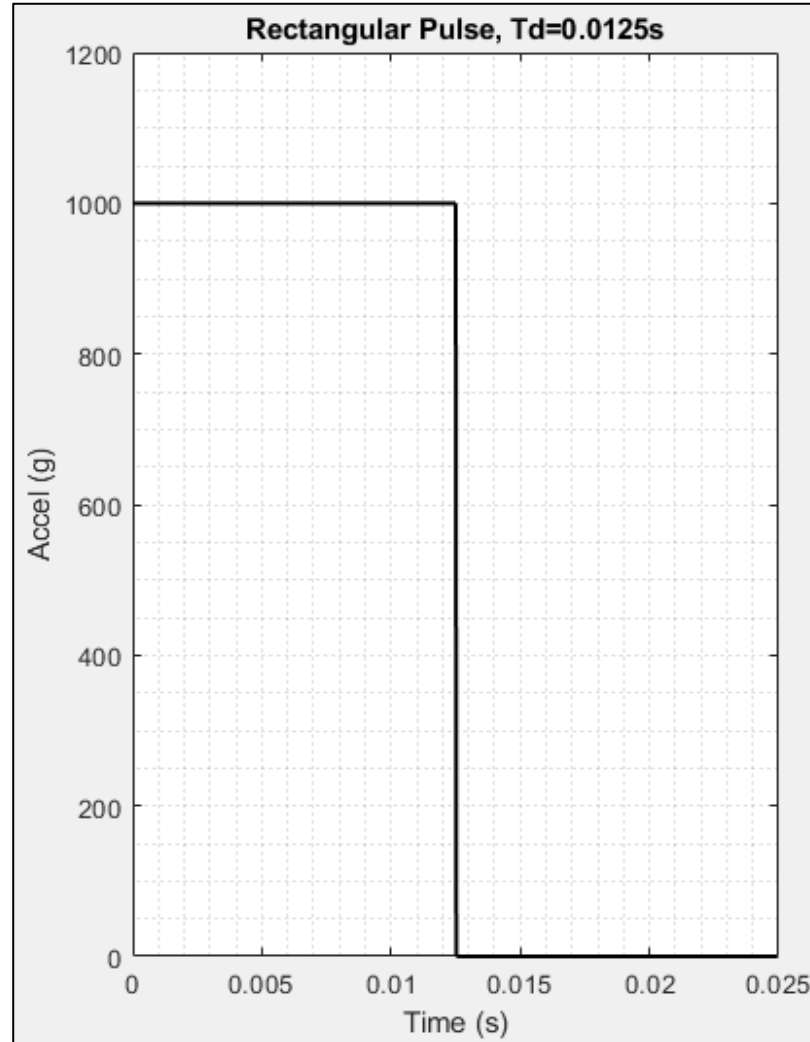
SCLV Dynamics Environment Workshop, 4 June, 2019

© 2019 California Institute of Technology. Government sponsorship acknowledged.



Rectangular Pulse & Square-Wave

- Ideal rectangular pulse of pulse width, T_d , and amplitude A .
- Undamped SDOF to ideal rectangular pulse modeled as,
- When the pulse is repeated ($A_w = \pm A$ & $T_p = 2T_d$) to form a square-wave, the periodic pulse can be approximate with Fourier series expansion to:
 - $Z(t) = \frac{4A_w}{\pi} \sum_{n=1,3,\dots} \frac{1}{n} \sin(n\Omega t)$
- Where $\Omega = 2\pi/T_p$.



Rectangular Pulse & Square-Wave SDOF Response

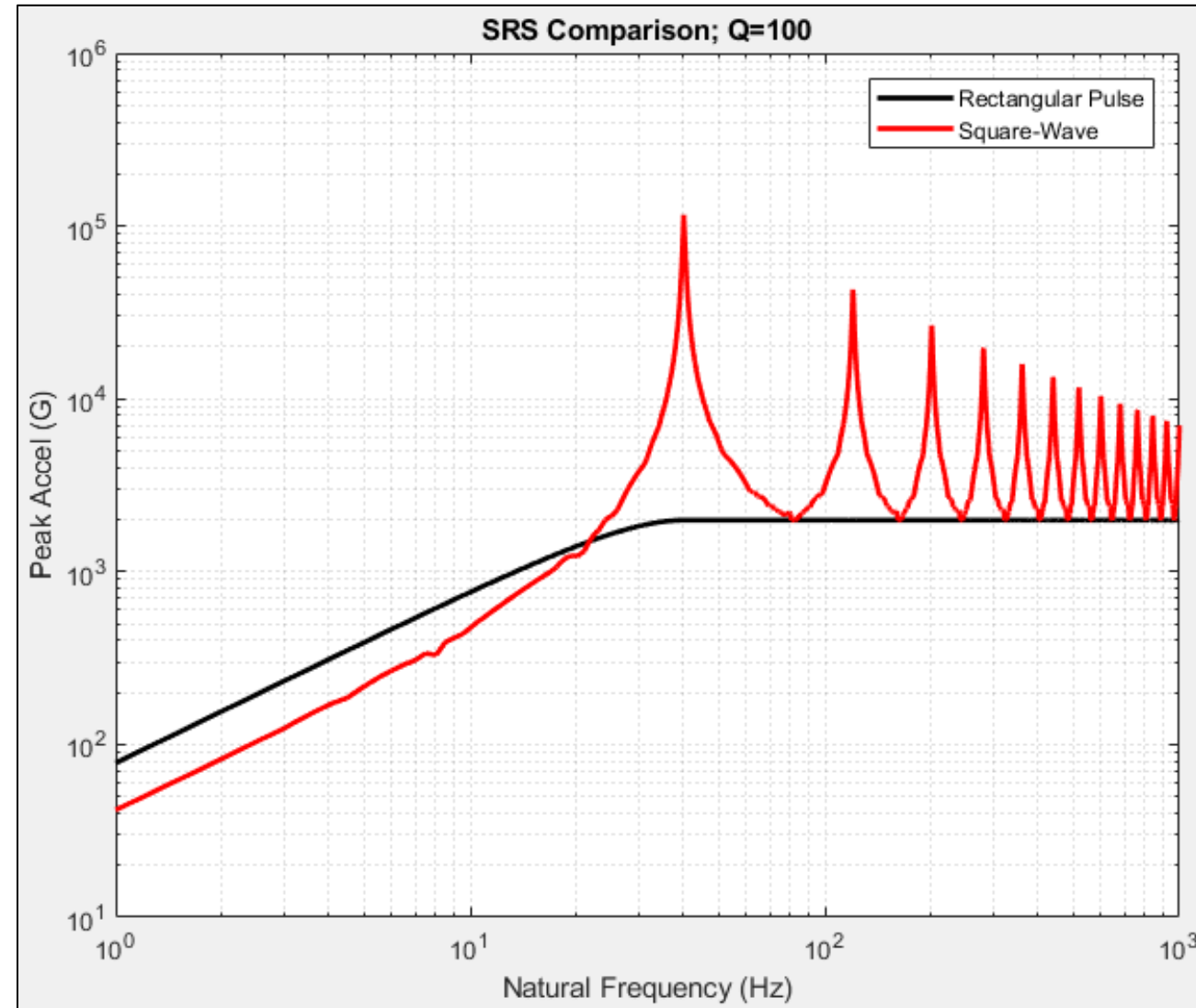
Dynamic Amplification Factor, R.

Undamped SDOF Response to Rectangular Pulse,

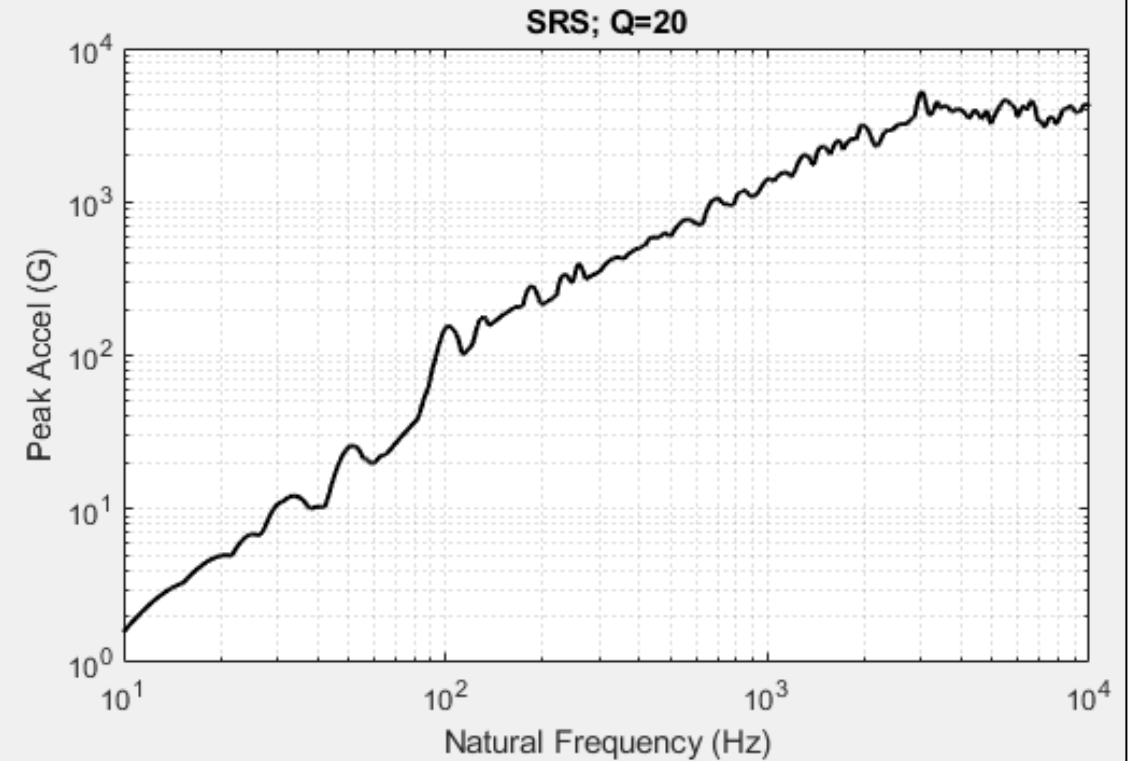
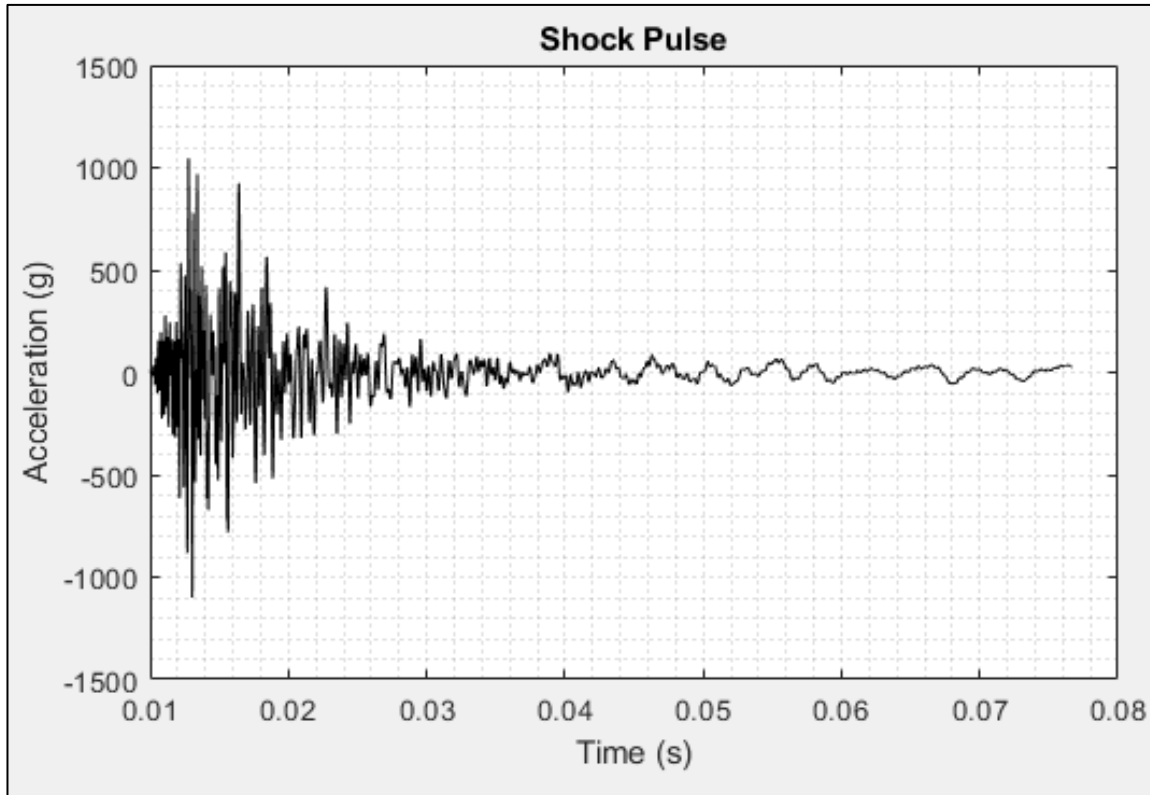
- For $T_d \geq 0.5T_n$ (Force-Vibration), where $T_n = 2\pi/\omega_n$,
 - $R_1 = 1 - \cos(\omega_n t)$ and $R_{1max} = 2$
- For $T_d < 0.5T_n$ (Residual-Response),
 - Free vibration with I.C. $R_1(T_p)$ & $\dot{R}_1(T_p)$.
 - & $R_{2max} = 2\sin(\frac{\pi T_d}{T_n})$.

Undamped SDOF Response to Square-Wave,

- $R = \sum_{n=1,3,\dots} \frac{(\frac{n\Omega}{\omega_n})^2}{1 - (\frac{n\Omega}{\omega_n})^2} * \frac{4}{n\pi} * \sin(n\Omega t)$
- Coupling can now occur when $\omega_n = n\Omega$.
- SRS indicates that, for $\omega_n \geq \Omega$, the peak response to the square-wave is equivalent to the max response to a rectangular pulse when $\omega_n = (n+1)\Omega$.



Repetitive Shock Description



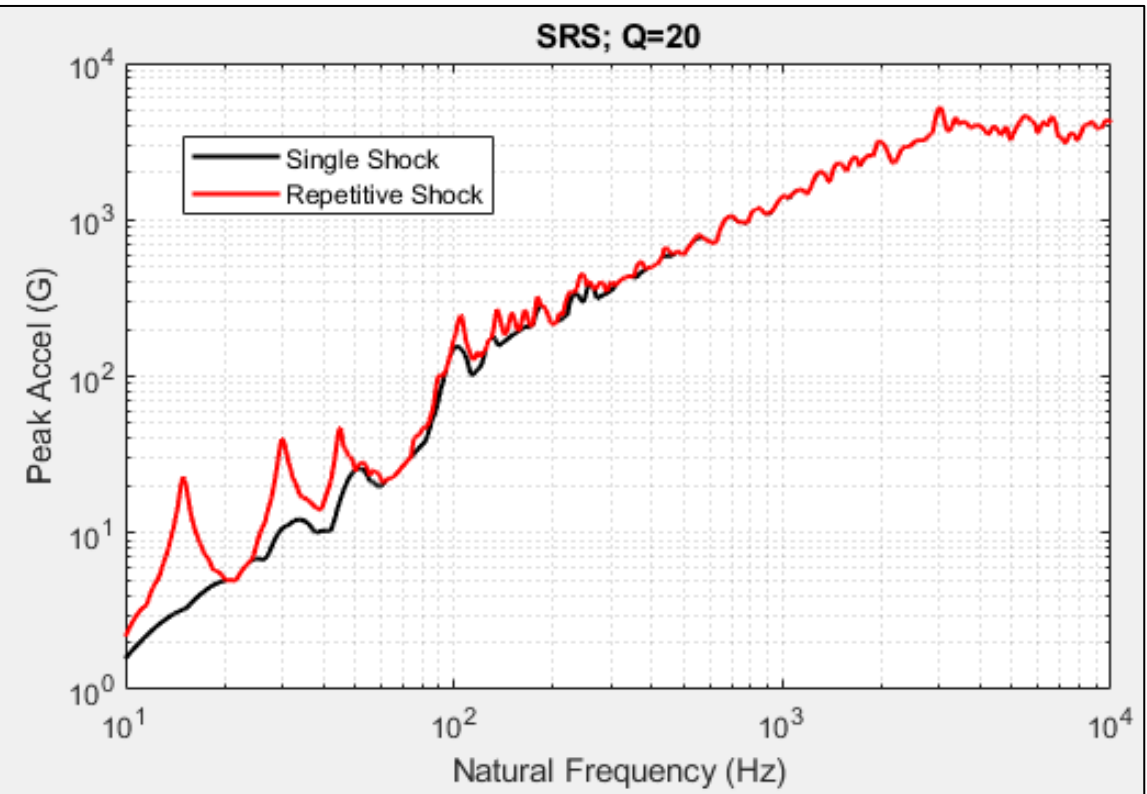
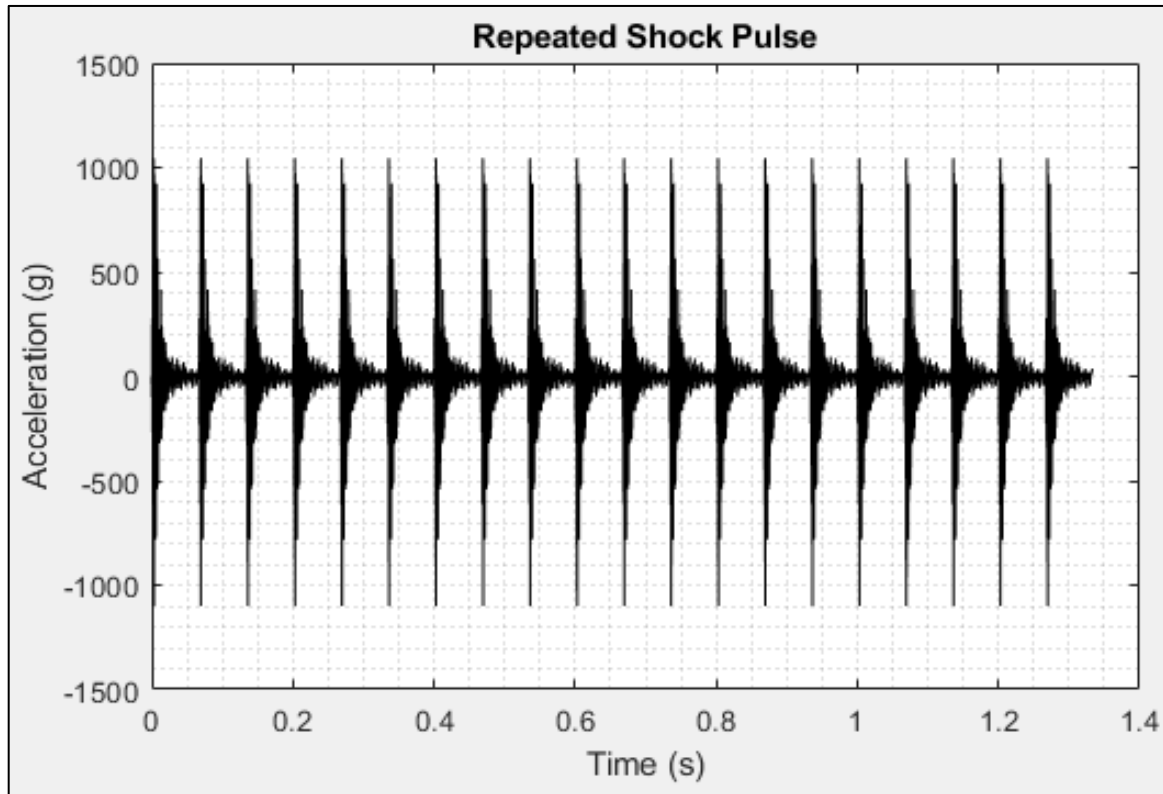
Single Shock Pulse Statistics

Amplitude Stats

mean = 0.0
std dev = 129.4
RMS = 129.4
skewness = 0.116
kurtosis = 18.02

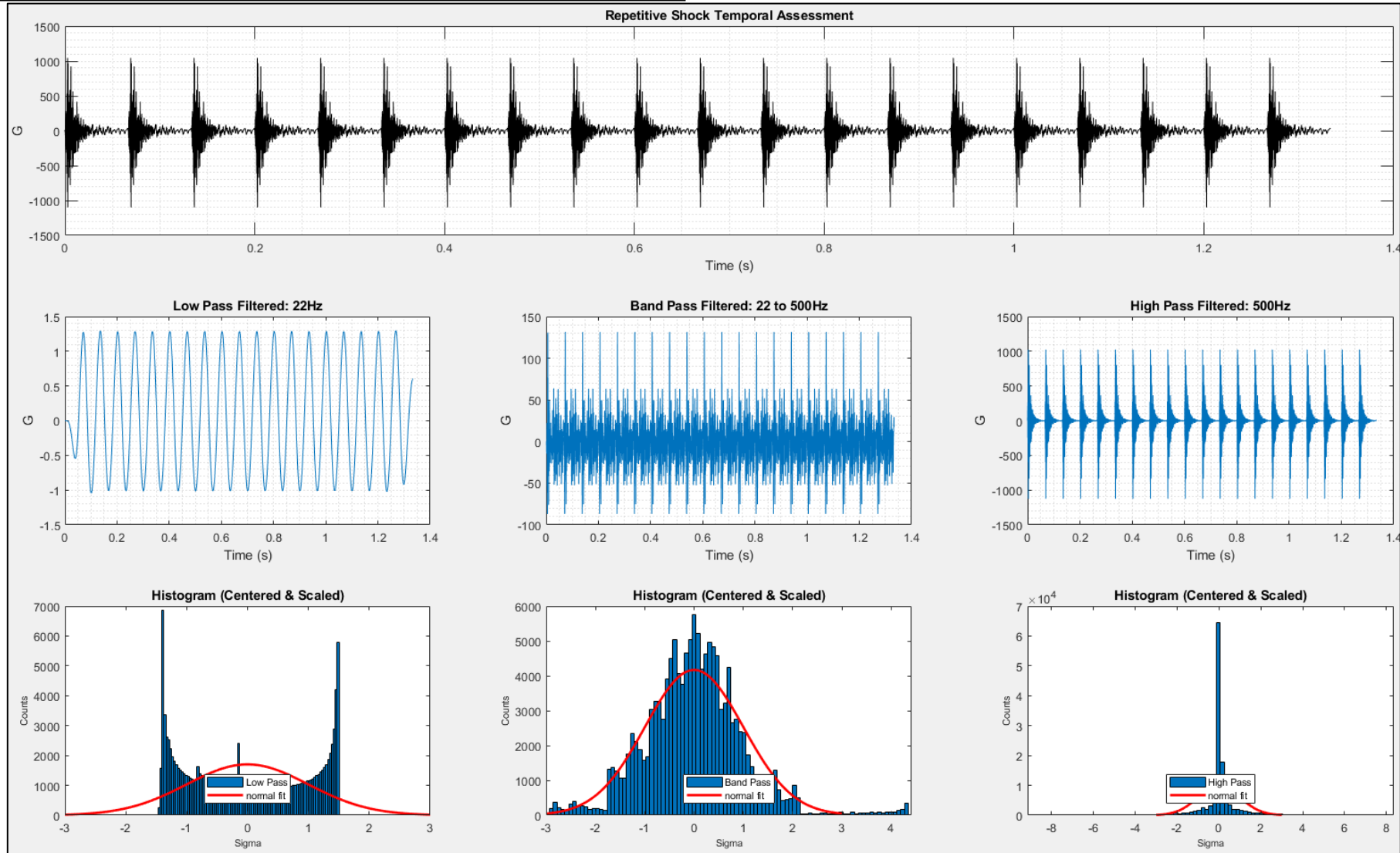
Maximum = 1045
Minimum = -1100
Crest Factor = 8.497

Repetitive Shock Description Cont'd...

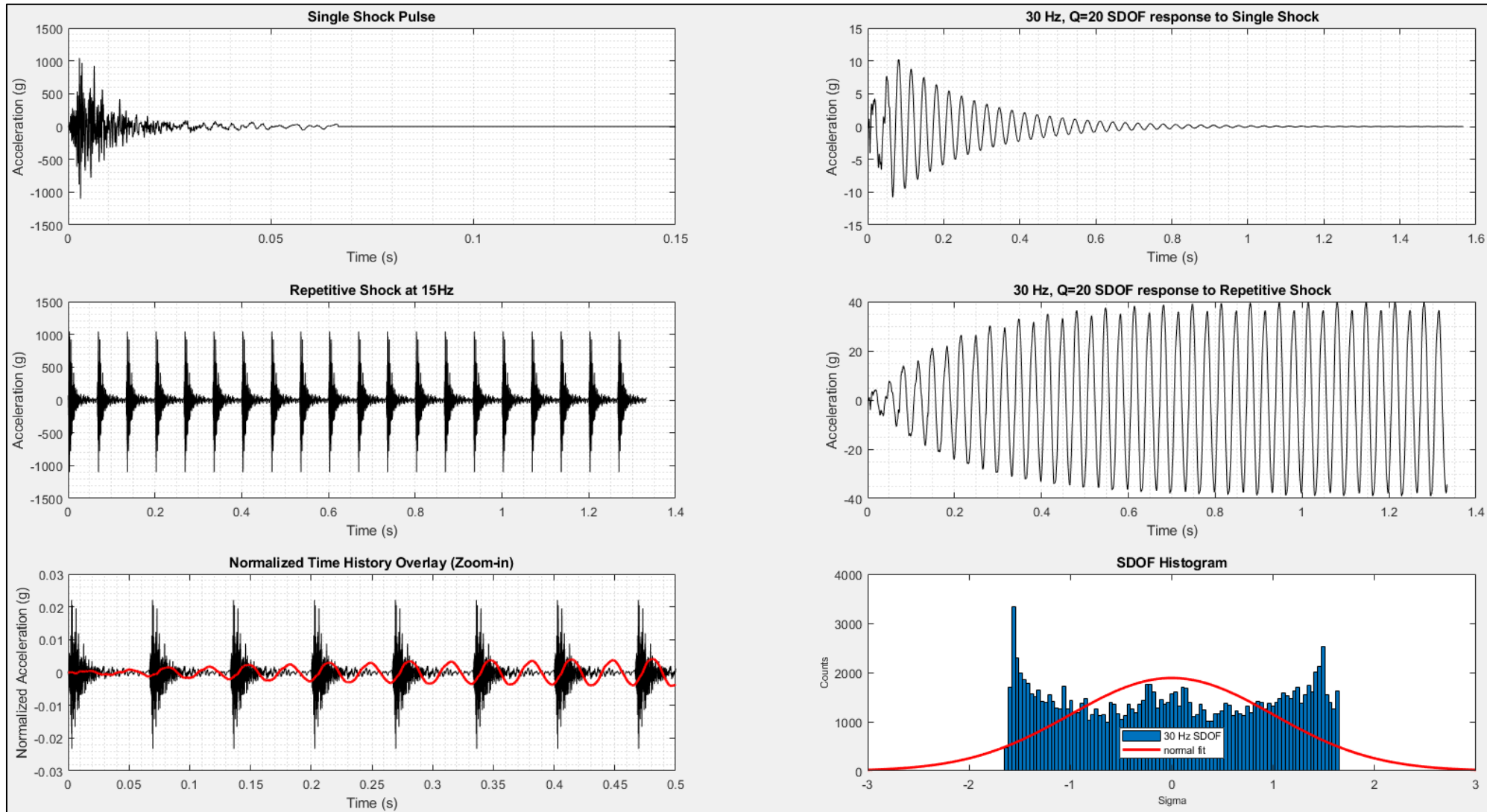


Similar observations as the rectangular pulse and square-wave example.

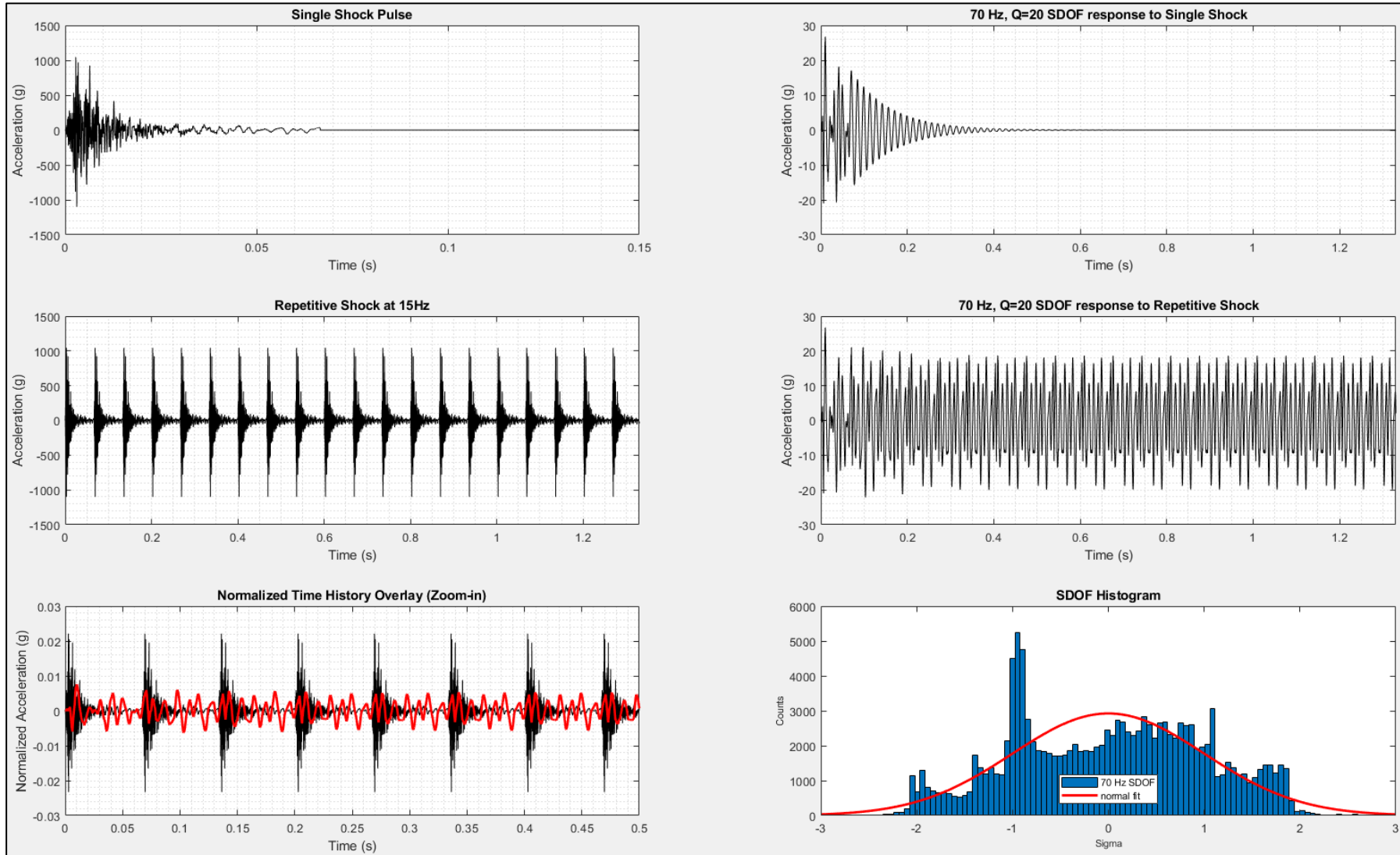
Temporal Characteristics



SDOF Response



SDOF Response Cont'd...



SDOF Response Cont'd...

